

# 22KW DC/DC Graphical User Interface (GUI) Introduction



## **Overview of CAN**

CAN Features:

- two-wire(differential signal) serial
- half duplex
- 1Mbit/s maximum
- Muti-Master network

Why is CAN used?

- Robust in noisy environments
- Reliable: built-in error confinement and detection
  - High speed
  - Cost effective



#### CAN Open Systems Interconnection (OSI)



Figure 1. The Layered ISO 11898 Standard Architecture

#### USB-CAN Tools and GUI

- The USB to CAN tools/adapters (CAN Analyzers) enable simple connection between CAN networks and a PC.
- CREE's GUI for its 22KW OBC also relies on a unique driver.
  - Thus, the GUI can only work with USBCAN-I hardware from GCAN.
  - Without this restriction any other USB to CAN tools could be used.



#### CAN Network and CAN Data Frame Format



Figure3. Extended CAN (CAN2.0B) frame format

- Only 29-bit Identifier and Data Bytes are used by users.
- Remaining bits are calculated and stuffed by CAN hardware.



#### **GUI CAN Data Format**

If you don't have GCAN tools, you can also send command to adjust the output voltage in the data format described below without visually displaying. You also have to judge if there is warning in the data stream.

Message Identifier: 0x18A5E5F4					
Data	Byte0 = <b>01</b>	Byte1= <b>00</b>	Byte2+Byte3	Byte4+Byte5 = 0x <b>12C0</b>	Byte6+Byte7 = 0x <mark>0168</mark>
Property	Charging	On	Reserved	DC Voltage:	DC Current:
	Mode; Full Bridge		0xFFFE	0x <b>12C0</b> *0.1V = 480V	0x <b>0168</b> *0.1A = 36A

Table 7: Example of Control Command

For example, use "0x18A5E5F4" as the message identifier and "0x0100FFFF12C00168" as CAN data to set the OBC to 480V with full current capacity. The first byte in the CAN instruction needs to match the real work mode situation when the second byte is zero or the instruction will be ignored by the reference board. The voltage control message only matters in charging mode because the output voltage is fixed in discharging mode.

For other frames, please refer to section 12.2/12.3 in user's guide.



#### **GUI Execution**

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		~
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i xiis.nlp 5/25/2016 2:32 PM NLP File 28 KB	Code: 0400h RxErrCount: 0000h TxErrCount: 0000h	

Step 1: Start the program after hardware connection is done. Connect USB port to PC and CAN port to connector J11 of OBC.

Step 2: Click "connect" to setup the communication.

Note: Microsoft C# visual studio was used to develop the GUI application. Installation is not needed.

#### The CREE GUI Overview

- The Cree GUI is dependent on the GCAN tool and its driver.
- Raw data and processed information are displayed in different tab pages.



### GUI Windows: CAN Status Tab

	Click to show CAN Status into. Display	. (Default)
	💀 Cree Monitor	– 🗆 X
	Setup CIN Baudrate 250 kBt/sec v Disconnect Reset Readinfo	Raw data to send manually
	CANStatus     biOBC       Write Messages     ID (Hex):       IBASESF4     ✓ Extended       8	01 68 Send
	Message     Reading       Rec: Time:10:30:38:346     ID:1AB2F4E5h Format:Data     Type:Exten     Data:00     0D     00     00       Rec: Time:10:30:38:347     ID:1AB2F4E5h Format:Data     Type:Exten     Data:03     5F     02     58     02       Rec: Time:10:30:38:347     ID:1AB2F4E5h Format:Data     Type:Exten     Data:00     0D     00	31 00 00 58 00 02 FF 00 FF 31 00 00 FF 00 FF 31 00 00 FF 00 FF
Information box:	Rec: Time:10:30:47:347 ID:1AB3F4E5h Format:Data Typ te Data:1D 00 00 01 00	FF 00 FF Raw data received
communication success.	Information Open Success Start CAN1 Success	Clear
	ErrorCode: 0000h RxErrCount: 00000h TxErrCount: 0000h	
Communication Status Bar	Step 3: Check for successful communicati If not, check CANH and CANL wire position	on setup. ns and if

control board has power.

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#### GUI Windows: biOBC Tab



### GUI Windows: biOBC Tab



Step 4: Open biOBC tab.



#### **GUI Specification Display Area**

General Info.	
SWVER:1.00	COMVER:1.00
BatVmin:200.0 V	BusVmin:380.0 V
BatVmax:800.0 V	BusVmax:900.0
Vbat_CCCP:610.0 V	
ChgCurMax:36.0 A	Get Para

SWVE:	Software Version, Ver1.00
COMVER:	Software Version for Communication, Ver 1.00
BatVmin:	Vmin at battery side, 200V
BatVmax:	Vmax at battery side, 800V
BusVmin:	Vmin at bus side, 380V
BusVmax:	Vmax at bus side, 900V
Vmax_CCCP:	Max voltage (610V) with Max Current (36A): 22KW/610V/36A.
ChgCurMax:	Max Current in charging mode, 36.0A



#### **GUI Reminder Display Area**



#### Note: Most reminders are invisible during normal operation.



#### **GUI** Operational Information Display





#### GUI Voltage/Current Control Area

1. Referring to Chapter 6 in the Users' Guide, select the right power direction based on the set-up connection.



Take 650V input and charging mode as example



CANStatus biOBC BAT Side Info BUS Info	<b>CANSE</b> 2. Verify the sample value of input voltage. Take 650V at bus side terminals for example.
Vdc: 0.1 V Idc: 0.0 A Vbus: 4.9 V Ibus: 0.0 A	Vdc: 0.0 V Idc: 0.0 A Vbus: 650.6 V Ibus: 0.0 A
Vbus: Ibus:	Vbus: Ibus:
1. Send OFF command to converter	Current Work Mode:
before applying DC input.	CLLC Control CMD
Power Direction ON/OFF	Power Direction ON/OFF
Charge O Discharge O ON OFF	Charge O Discharge O ON OFF
Topology     Vmax(V):     610.0     Ibat(A):     36.0	Topology Vmax(V): 610.0 Ibat(A): 36.0
Full Bridge O Half Bridge Send to OBC	Full Bridge O Half Bridge Send to OBC
SR Auto TurnOff	SR Auto TurnOff





BAT Side Info BUS Info	BAT Side Info BUS Info		
Vdc: 338.9 V Idc: 7.8 A Vbus: 650.3 V Ibus: 7.4 A	Vdc: 489.4 V Idc: 11.6 A Vbus: 650.3 V Ibus: 10.1 A		
6. Set reasonable voltage reference as desi 650V or 900V. That is 340V~490.8V for 650	red when the input voltage is at about OV input. Input tolerance is 3V.		
CLLC Control CMD   Power Direction   ON/OFF   One Charge   Discharge	CLLE Control CMD Power Direction ON/OFF ON OFF		
Topology Vmax(V): 340.0 Ibat(A): 36.0   Ibat(A): Send to OBC	Topology Vmax(V): 490.0 Ibat(A): 36.0   Image: Topology Ibat(A): 36.0   Image: Topology Ibat(A): 36.0		
SR Auto TurnOn BAT<<< <bus@full bridge<="" th=""><th>SR Auto TurnOn BAT&lt;&lt;&lt;<bus@full bridge<="" th=""></bus@full></th></bus@full>	SR Auto TurnOn BAT<<< <bus@full bridge<="" th=""></bus@full>		
SR is enabled automatically.			





